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## Steering by-wire in the Ford F-150

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### Features

- Computer control of steering
- Measure steering wheel position
- Driver override by grabbing the steering wheel
- CAN and USB interfaces
- No modifications to vehicle
- Signal passthrough on power off

### Applications

- Driverless car research
- Advanced Driver Assist (ADAS) research

### Description

The Dataspeed Inc. Steer-By-Wire interface enables computer control of the steering wheel in a safe and effective manner. This plug-in ready kit requires no modification to the factory harnessing and can be installed in minutes. Industry standard CAN and USB networks enable control and monitoring of the steering system.



## Contents

<b>1</b>	<b>Connector Pin Description</b>	<b>3</b>
1.1	CAN/DB9 Connector . . . . .	3
1.2	USB Connector . . . . .	3
<b>2</b>	<b>Electrical Characteristics</b>	<b>3</b>
<b>3</b>	<b>Mechanical Drawings</b>	<b>4</b>
<b>4</b>	<b>CAN Messages</b>	<b>5</b>
4.1	Steering . . . . .	6
4.1.1	Command . . . . .	6
4.1.2	Report . . . . .	7
4.2	Turn Signal Command . . . . .	8
4.3	Miscellaneous Report . . . . .	9
4.4	Wheel Speed . . . . .	12
4.5	Acceleration . . . . .	13
4.6	Angular Rates . . . . .	14
4.7	Wheel Position . . . . .	15
4.8	Tire Pressure . . . . .	16
4.9	Fuel Level . . . . .	17
4.10	Surround . . . . .	18
4.11	Brake Info . . . . .	19
4.12	Throttle Info . . . . .	21
4.13	Driver Assist . . . . .	22
4.14	License . . . . .	23
4.14.1	Feature: Base . . . . .	23
4.14.2	MAC Address . . . . .	24
4.14.3	Build Date (part 0) . . . . .	25
4.14.4	Build Date (part 1) . . . . .	26
4.14.5	VIN (part 0) . . . . .	27
4.14.6	VIN (part 1) . . . . .	28
4.14.7	VIN (part 2) . . . . .	29
4.15	Version . . . . .	30
<b>5</b>	<b>Function</b>	<b>31</b>
<b>6</b>	<b>Supported Vehicles</b>	<b>31</b>
<b>7</b>	<b>Watchdog Counter</b>	<b>32</b>
7.1	Fault Conditions . . . . .	32
7.2	Fault Actions . . . . .	32

## DISCLAIMER:

This product is intended for research purposes only. Steps have been taken to ensure function on power or communication loss. However, in no event shall Dataspeed Inc. be liable for any direct, indirect, punitive, incidental, special consequential damages, to property or life, whatsoever arising out of or connected with the use or misuse of its products.

## 1 Connector Pin Description

### 1.1 CAN/DB9 Connector

The CAN/DB9 connector is used for power and CAN communication. Short pins 1 and 6 together to activate the digital input.

Table 1: CAN/DB9 connector pin description.

Pin	Symbol	Description
1	DIGIN	Digital Input
2	CANL	CAN Low
3	GND	Ground
4	IGNITION	Ignition (12V)
5	NC	No Connect
6	GND	Ground
7	CANH	CAN High
8	NC	No Connect
9	POWER	Power (12V)

### 1.2 USB Connector

The USB connector is used for introspection and firmware upgrade.

## 2 Electrical Characteristics

Table 2: Electrical Characteristics.

Characteristic	Min	Typ	Max	Units	Conditions
VIGNITION ON	9	12	16	V	
VIGNITION OFF	-0.3	0	2	V	
VPOWER	9	12	16	V	
IPOWER		200		mA	VPOWER=12V, VIGNITION>9V
IPOWER			0.1	mA	VPOWER=12V, VIGNITION<2V
Temperature	-40		+85	°C	

## 3 Mechanical Drawings

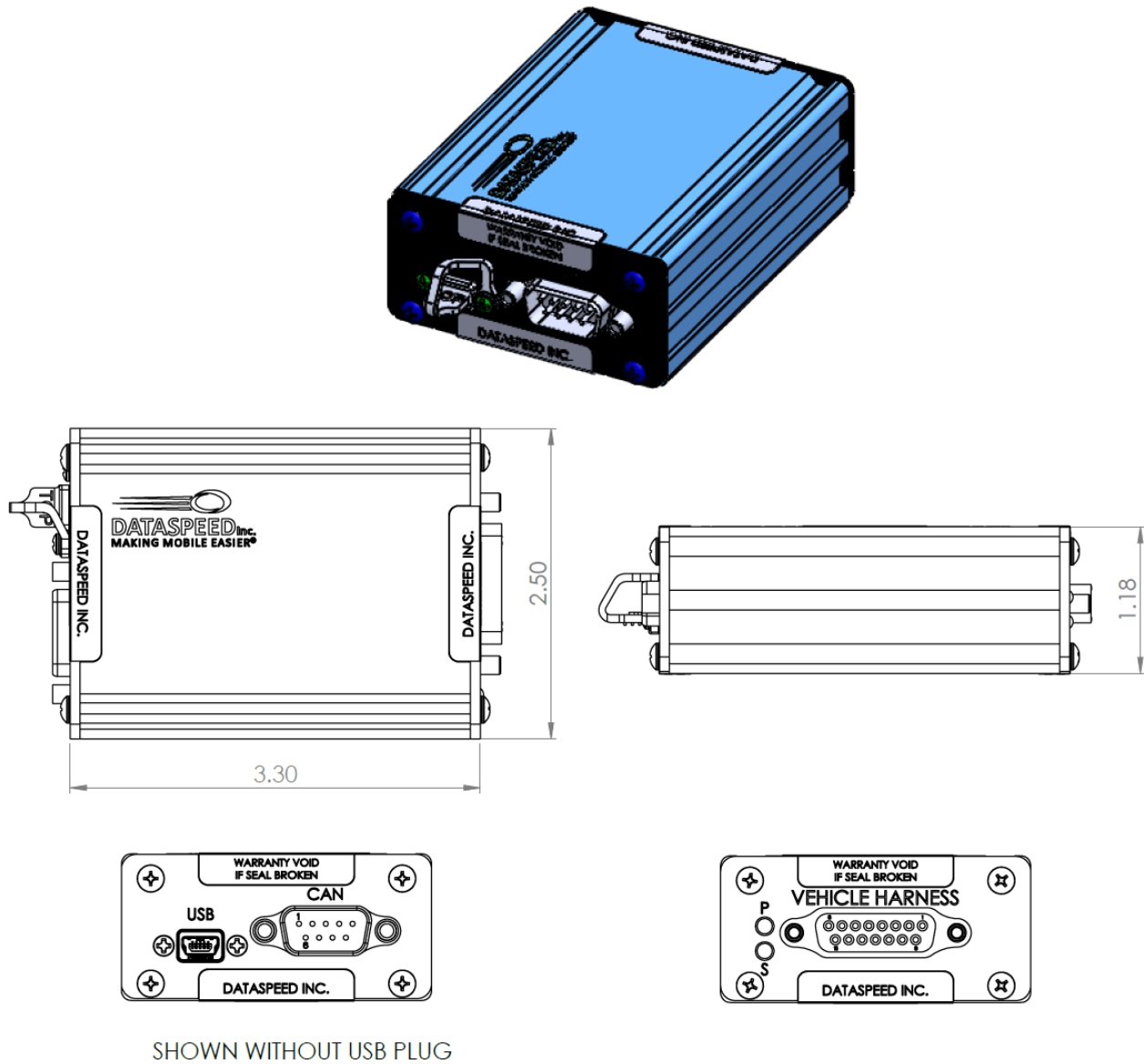


Figure 1: Mechanical Drawing

## 4 CAN Messages

Table 3: CAN bus configuration.

Parameter	Value	Units
Terminated	Yes	120 $\Omega$
BitRate	500	k
$t_q$	200	ns
SyncSeg	1	$t_q$
PropSeg	3	$t_q$
PhaseSeg1	3	$t_q$
PhaseSeg2	3	$t_q$
SyncJumpWidth	2	$t_q$

## 4.1 Steering

### 4.1.1 Command

Message ID: 0x064  
 Receive Rate: 20ms  
 Receive Timeout: 100ms

Table 4: Steering Command CAN Message Description.

Byte	Bits	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0	7:0	SCMD<7:0>							
1	15:8	SCMD<15:8>							
2	23:16	—	—	—	QUIET	—	IGNORE	CLEAR	EN
3	31:24	SVEL							
4	39:32	—	—	—	—	—	—	—	—
5	47:40	—	—	—	—	—	—	—	—
6	55:48	—	—	—	—	—	—	—	—
7	63:56	COUNT							

bit 0-15      **SCMD:** Steering Command  
                  0x1664 = 570° left  
                  0x0001 = 0.1° left  
                  0x0000 = 0.0° center  
                  0xFFFF = 0.1° right  
                  0xE9BC = 570° right

bit 16        **EN:** Enable request  
                  1 = enable  
                  0 = disable

bit 17        **CLEAR:** Clear driver override flag  
                  1 = request clear of driver override  
                  0 = normal operation

bit 18        **IGNORE:** Ignore driver override  
                  1 = ignore  
                  0 = normal

bit 19        **Unimplemented:** Set to '0'

bit 20        **QUIET:** Disable driver override audible warning  
                  1 = disable  
                  0 = normal

bit 21-23     **Unimplemented:** Set to '0'

bit 24-31     **SVEL:** Steering Velocity  
                  0x00 = 0°/s = 500°/s  
                  0x01 = 2°/s  
                  0x02 = 4°/s  
                  0xFA = 500°/s

bit 32-55     **Unimplemented:** Set to '0'

bit 56-63     **COUNT:** Optional watchdog counter

Note: The following requirements must be met to engage steering.

Steering wheel torque:  $-1.5 \leq \text{TORQUE} < 1.5$   
 Steering wheel angle velocity:  $-50^\circ/\text{s} < \text{VELOCITY} < 50^\circ/\text{s}$

# Ford F-150 Steer-By-Wire

## 4.1.2 Report

Message ID: 0x065  
Transmit Rate: 20ms

Table 5: Steering Report CAN Message Description.

Byte	Bits	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0	7:0	ANGLE<7:0>							
1	15:8	ANGLE<15:8>							
2	23:16	CMD<7:0>							
3	31:24	CMD<15:8>							
4	39:32	SPEED<7:0>							
5	47:40	SPEED<15:8>							
6	55:48	TORQUE							
7	63:56	TMOUT	FLTCAL	FLT2	FLT1	FLTWDC	FLTPWR	OVERRIDE	EN

- bit 0-15      **ANGLE:** Steering wheel angle  
0x1664 = 570° left  
0x0001 = 0.1° left  
0x0000 = 0.0° center  
0xFFFF = 0.1° right  
0xE9BC = 570° right
- bit 16-31      **CMD:** Reported steering wheel command  
0x1664 = 570° left  
0x0001 = 0.1° left  
0x0000 = 0.0° center  
0xFFFF = 0.1° right  
0xE9BC = 570° right
- bit 32-47      **SPEED:** Vehicle speed  
0 = 0.00 kph  
1 = 0.01 kph  
65535 = 655.35 kph
- bit 48-55      **TORQUE:** Steering column torque  
0x7F = 7.9375 Nm  
0x01 = 0.0625 Nm  
0x00 = 0.0000 Nm  
0xFF = -0.0625 Nm  
0x80 = -8.0000 Nm
- bit 56      **EN:** Enabled  
0 = disabled. SCMD ignored.  
1 = enabled. No timeouts or overrides have occurred.
- bit 57      **OVERRIDE:** Driver Override (Cleared on rising edge of EN bit in command message)  
0 = No Override (|TORQUE| < 4.5 Nm or ignored)  
1 = Driver Override (|TORQUE| ≥ 4.5 Nm) (configurable)
- bit 58      **FLTPWR:** Power fault: 0 = No fault, 1 = Fault
- bit 59      **FLTWDC:** Watchdog Counter fault: 0 = No fault, 1 = Fault
- bit 60      **FLT1:** Channel 1 fault: 0 = No fault, 1 = Fault
- bit 61      **FLT2:** Channel 2 fault: 0 = No fault, 1 = Fault
- bit 62      **FLTCAL:** Calibration fault: 0 = No fault, 1 = Fault  
Disconnecting the vehicle battery will cause the production vehicle to lose steering calibration. Drive at least 25 mph for at least 10 seconds in a straight line (see vehicle manual).
- bit 63      **TMOUT:** Timeout: 0 = Command is fresh, 1 = Command timeout after 100ms

## 4.2 Turn Signal Command

Message ID: 0x068  
Receive Rate: 50ms  
Receive Timeout: 200ms

Table 6: Turn Signal Command CAN Message Description.

Byte	Bits	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0	7:0	—	—	—	—	—	—	TRNCMD	

bit 0-1      **TRNCMD:** Turn Signal Command  
0 = None  
1 = Left  
2 = Right  
3 = Not Used

bit 7-2      **Unimplemented:** Set to '0'

Note: The turn-signal command will be rejected if OVERRIDE=1 for any of brake/throttle/steering. This is silent, there is no signal to report that the command was rejected.



## 4.3 Miscellaneous Report

Message ID: 0x069  
Transmit Rate: 50ms

Table 7: Miscellaneous Report CAN Message Description.

Byte	Bits	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0	7:0	WIPER				HIBEAM		TRNSTAT	
1	15:8	RINC	CNCL	RES	OFF	ON	AMBIENT		
2	23:16	FLTBUS	LKAEN	GDEC	GINC	SDEC	SINC	RESCNCLONOFF	
3	31:24	PABAG	PDECT	TRUNK	HOOD	DOORR	DOORL	DOORP	DOORD
4	39:32	RDEC	LDRHT	LDLFT	LDDWN	LDUP	LDOK	BELTP	BELTD
5	47:40	—	—	—	—	—	—	—	—
6	55:48	—	—	—	—	—	—	—	—
7	63:56	OTEMP							

bit 0-1 **TRNSTAT:** Turn signal status  
0 = None  
1 = Left  
2 = Right  
3 = Not Used

bit 2-3 **HIBEAM:** High-beam status (See Table 8)

bit 4-7 **WIPER:** Wiper status (See Table 9)

bit 8-10 **AMBIENT:** Ambient light status (See Table 10)

bit 11 **ON:** ACC on button: 0 = Not pressed, 1 = Pressed

bit 12 **OFF:** ACC off button: 0 = Not pressed, 1 = Pressed

bit 13 **RES:** ACC resume button: 0 = Not pressed, 1 = Pressed

bit 14 **CNCL:** ACC cancel button: 0 = Not pressed, 1 = Pressed

bit 15 **RINC:** ACC increment resume button: 0 = Not pressed, 1 = Pressed

bit 16 **ONOFF:** ACC on/off button: 0 = Not pressed, 1 = Pressed

bit 17 **RESCNCL:** ACC resume/cancel button: 0 = Not pressed, 1 = Pressed

bit 18 **SINC:** ACC increment set speed button: 0 = Not pressed, 1 = Pressed

bit 19 **SDEC:** ACC decrement set speed button: 0 = Not pressed, 1 = Pressed

bit 20 **GINC:** ACC increment following gap button: 0 = Not pressed, 1 = Pressed

bit 21 **GDEC:** ACC decrement following gap button: 0 = Not pressed, 1 = Pressed

bit 22 **LKAEN:** Lane Keeping Assist (LKA) on/off button: 0 = Not pressed, 1 = Pressed

bit 23 **FLTBUS:** CAN bus fault: 0 = No Fault, 1 = Fault

bit 24 **DOORD:** Driver door, 0 = Closed, 1 = Open

bit 25 **DOORP:** Passenger door, 0 = Closed, 1 = Open

bit 26 **DOORL:** Rear left door, 0 = Closed, 1 = Open

bit 27 **DOORR:** Rear right door, 0 = Closed, 1 = Open

bit 28 **HOOD:** Hood, 0 = Closed, 1 = Open

bit 29 **TRUNK:** Trunk, 0 = Closed, 1 = Open

bit 30 **PDECT:** Passenger detect, 0 = No Passenger, 1 = Passenger

bit 31 **PABAG:** Passenger airbag, 0 = Disabled, 1 = Enabled

bit 32 **BELTD:** Driver seat belt, 0 = Unbuckled, 1 = Buckled

bit 33 **BELTP:** Passenger seat belt, 0 = Unbuckled, 1 = Buckled

## Ford F-150 Steer-By-Wire

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bit 34	<b>LDOK:</b> Left D-Pad OK button: 0 = Not pressed, 1 = Pressed
bit 35	<b>LDUP:</b> Left D-Pad Up button: 0 = Not pressed, 1 = Pressed
bit 36	<b>LDDWN:</b> Left D-Pad Down button: 0 = Not pressed, 1 = Pressed
bit 37	<b>LDLFT:</b> Left D-Pad Left button: 0 = Not pressed, 1 = Pressed
bit 38	<b>LDRHT:</b> Left D-Pad Right button: 0 = Not pressed, 1 = Pressed
bit 39	<b>RDEC:</b> ACC increment resume button: 0 = Not pressed, 1 = Pressed
bit 40-55	<b>Unimplemented:</b> Set to '0'
bit 56-63	<b>OTEMP:</b> Outside Air Temperature: 0x00 = -40.0 °C 0x5F = -0.5 °C 0x60 = 0.0 °C 0x61 = 0.5 °C 0xFD = 86.5 °C 0xFE = Unknown 0xFF = Invalid

Table 8: Enumeration values of the **HIBEAM** signal

Value	Enum
0	NULL
1	FLASH_TO_PASS
2	HIGH
3	—

Table 9: Enumeration values of the **WIPER** signal

Value	Enum
0	OFF
1	AUTO_OFF
2	OFF_MOVING
3	MANUAL_OFF
4	MANUAL_ON
5	MANUAL_LOW
6	MANUAL_HIGH
7	MIST_FLICK
8	WASH
9	AUTO_LOW
10	AUTO_HIGH
11	COURTESY_WIPE
12	AUTO_ADJUST
13	RESERVED
14	STALLED
15	NO_DATA

Table 10: Enumeration values of the **AMBIENT** signal

Value	Enum
0	DARK
1	LIGHT
2	TWILIGHT
3	TUNNEL_ON
4	TUNNEL_OFF
5	—
6	—
7	NO_DATA

## 4.4 Wheel Speed

Message ID: 0x06A  
Transmit Rate: 10ms

Table 11: Wheel Speed CAN Message Description.

Byte	Bits	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0	7:0	FL<7:0>							
1	15:8	FL<15:8>							
2	23:16	FR<7:0>							
3	31:24	FR<15:8>							
4	39:32	RL<7:0>							
5	47:40	RL<15:8>							
6	55:48	RR<7:0>							
7	63:56	RR<15:8>							

bit 0-15      **FL:** Front Left Wheel Speed  
0x7FFF = 327.67 rad/s  
0x0001 = 0.01 rad/s  
0x0000 = 0.00 rad/s  
0xFFFF = -0.01 rad/s  
0x8000 = -327.68 rad/s

bit 16-31    **FR:** Front Right Wheel Speed  
0x7FFF = 327.67 rad/s  
0x0001 = 0.01 rad/s  
0x0000 = 0.00 rad/s  
0xFFFF = -0.01 rad/s  
0x8000 = -327.68 rad/s

bit 32-47    **RL:** Rear Left Wheel Speed  
0x7FFF = 327.67 rad/s  
0x0001 = 0.01 rad/s  
0x0000 = 0.00 rad/s  
0xFFFF = -0.01 rad/s  
0x8000 = -327.68 rad/s

bit 48-63    **RR:** Rear Right Wheel Speed  
0x7FFF = 327.67 rad/s  
0x0001 = 0.01 rad/s  
0x0000 = 0.00 rad/s  
0xFFFF = -0.01 rad/s  
0x8000 = -327.68 rad/s

## 4.5 Acceleration

Message ID: 0x06B  
Transmit Rate: 10ms

Table 12: Acceleration CAN Message Description.

Byte	Bits	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0	7:0	LAT<7:0>							
1	15:8	LAT<15:8>							
2	23:16	LONG<7:0>							
3	31:24	LONG<15:8>							
4	39:32	VERT<7:0>							
5	47:40	VERT<15:8>							

bit 0-15      **LAT:** Lateral acceleration  
0x7FFF = 327.67 m/s<sup>2</sup>  
0x0001 = 0.01 m/s<sup>2</sup>  
0x0000 = 0.00 m/s<sup>2</sup>  
0xFFFF = -0.01 m/s<sup>2</sup>  
0x8000 = -327.68 m/s<sup>2</sup>

bit 16-31    **LONG:** Longitudinal acceleration  
0x7FFF = 327.67 m/s<sup>2</sup>  
0x0001 = 0.01 m/s<sup>2</sup>  
0x0000 = 0.00 m/s<sup>2</sup>  
0xFFFF = -0.01 m/s<sup>2</sup>  
0x8000 = -327.68 m/s<sup>2</sup>

bit 32-47    **VERT:** Vertical acceleration  
0x7FFF = 327.67 m/s<sup>2</sup>  
0x0001 = 0.01 m/s<sup>2</sup>  
0x0000 = 0.00 m/s<sup>2</sup>  
0xFFFF = -0.01 m/s<sup>2</sup>  
0x8000 = -327.68 m/s<sup>2</sup>

## 4.6 Angular Rates

Message ID: 0x6C  
Transmit Rate: 10ms

Table 13: Angular Rates CAN Message Description.

Byte	Bits	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0	7:0	ROLL<7:0>							
1	15:8	ROLL<15:8>							
2	23:16	YAW<7:0>							
3	31:24	YAW<15:8>							

bit 0-15      **ROLL:** Roll rate  
0x7FFF = 6.5534 rad/s  
0x0001 = 0.0002 rad/s  
0x0000 = 0.0000 rad/s  
0xFFFF = -0.0002 rad/s  
0x8000 = -6.5536 rad/s

bit 16-31    **YAW:** Yaw rate  
0x7FFF = 6.5534 rad/s  
0x0001 = 0.0002 rad/s  
0x0000 = 0.0000 rad/s  
0xFFFF = -0.0002 rad/s  
0x8000 = -6.5536 rad/s

## 4.7 Wheel Position

Message ID: 0x070  
Transmit Rate: 20ms

Table 14: Wheel Position CAN Message Description.

Byte	Bits	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0	7:0	FL<7:0>							
1	15:8	FL<15:8>							
2	23:16	FR<7:0>							
3	31:24	FR<15:8>							
4	39:32	RL<7:0>							
5	47:40	RL<15:8>							
6	55:48	RR<7:0>							
7	63:56	RR<15:8>							

bit 0-15      **FL:** Front Left Wheel Position Counts  
0x7FFF = 32767  
0x0001 = 1  
0x0000 = 0  
0xFFFF = -1  
0x8000 = -32768

bit 16-31    **FR:** Front Right Wheel Position Counts  
0x7FFF = 32767  
0x0001 = 1  
0x0000 = 0  
0xFFFF = -1  
0x8000 = -32768

bit 32-47    **RL:** Rear Left Wheel Position Counts  
0x7FFF = 32767  
0x0001 = 1  
0x0000 = 0  
0xFFFF = -1  
0x8000 = -32768

bit 48-63    **RR:** Rear Right Wheel Position Counts  
0x7FFF = 32767  
0x0001 = 1  
0x0000 = 0  
0xFFFF = -1  
0x8000 = -32768

The conversion factor was experimentally determined to be 125.5 counts per revolution. It is recommended to experimentally calculate the conversion factor for a particular vehicle by comparing wheel position counts over time with wheel speeds.

## 4.8 Tire Pressure

Message ID: 0x071  
Transmit Rate: 500ms

Table 15: Tire Pressure CAN Message Description.

Byte	Bits	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0	7:0	FL<7:0>							
1	15:8	FL<15:8>							
2	23:16	FR<7:0>							
3	31:24	FR<15:8>							
4	39:32	RL<7:0>							
5	47:40	RL<15:8>							
6	55:48	RR<7:0>							
7	63:56	RR<15:8>							

bit 0-15      **FL:** Front Left Tire Pressure  
0 = 0 kPa  
1 = 1 kPa  
65535 = 65535 kPa

bit 16-31    **FR:** Front Right Tire Pressure  
0 = 0 kPa  
1 = 1 kPa  
65535 = 65535 kPa

bit 32-47    **RL:** Rear Left Tire Pressure  
0 = 0 kPa  
1 = 1 kPa  
65535 = 65535 kPa

bit 48-63    **RR:** Rear Right Tire Pressure  
0 = 0 kPa  
1 = 1 kPa  
65535 = 65535 kPa



## 4.9 Fuel Level

Message ID: 0x072  
Transmit Rate: 100ms

Table 16: Fuel Level CAN Message Description.

Byte	Bits	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0	7:0	FUEL<7:0>							
1	15:8	FUEL<15:8>							

bit 0-15      **FUEL:** Fuel Level  
0x0398 = 100.0000%  
0x0001 = 0.108696%  
0x0000 = 0.000000%  
0xFFFF = -0.108696%

## 4.10 Surround

Message ID: 0x073  
Transmit Rate: 200ms

Table 17: Surround CAN Message Description.

Byte	Bits	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0	7:0	BLISRE	BLISRA	CTARE	CTARA	BLISLE	BLISLA	CTALE	CTALA
1	15:8	SONAR01				SONAR00			
2	23:16	SONAR03				SONAR02			
3	31:24	SONAR05				SONAR04			
4	39:32	SONAR07				SONAR06			
5	47:40	SONAR09				SONAR08			
6	55:48	SONAR11				SONAR10			
7	63:56	FLTSNR	ENSNR	—	—	—	—	—	—

- bit 0      **CTALA:** Cross Traffic Alert left alert  
0 = No Alert, 1 = Alert
- bit 1      **CTALE:** Cross Traffic Alert left enabled  
0 = Disabled, 1 = Enabled
- bit 2      **BLISLA:** Blind Spot Information System left alert  
0 = No Alert, 1 = Alert
- bit 3      **BLISLE:** Blind Spot Information System left enabled  
0 = Disabled, 1 = Enabled
- bit 4      **CTARA:** Cross Traffic Alert right alert  
0 = No Alert, 1 = Alert
- bit 5      **CTARE:** Cross Traffic Alert right enabled  
0 = Disabled, 1 = Enabled
- bit 6      **BLISRA:** Blind Spot Information System right alert  
0 = No Alert, 1 = Alert
- bit 7      **BLISRE:** Blind Spot Information System right enabled  
0 = Disabled, 1 = Enabled
- bit 8-11   **SONAR00:** Sonar front left side  
0x0 = Nothing Detected  
0x1 = 0.30 m  
0x2 = 0.45 m  
0xF = 2.40 m
- bit 12-15   **SONAR01:** Sonar front left corner (same as SONAR00)
- bit 16-19   **SONAR02:** Sonar front left center (same as SONAR00)
- bit 20-23   **SONAR03:** Sonar front right center (same as SONAR00)
- bit 24-27   **SONAR04:** Sonar front right corner (same as SONAR00)
- bit 28-31   **SONAR05:** Sonar front right side (same as SONAR00)
- bit 32-35   **SONAR06:** Sonar rear left side (same as SONAR00)
- bit 36-39   **SONAR07:** Sonar rear left corner (same as SONAR00)
- bit 40-43   **SONAR08:** Sonar rear left center (same as SONAR00)
- bit 44-47   **SONAR09:** Sonar rear right center (same as SONAR00)
- bit 48-51   **SONAR10:** Sonar rear right corner (same as SONAR00)
- bit 52-55   **SONAR11:** Sonar rear right side (same as SONAR00)
- bit 56:61   **Unimplemented:** Set to '0'
- bit 62      **ENSNR:** Sonar Enabled  
0 = Disabled, 1 = Enabled
- bit 63      **FLTSNR:** Sonar Fault  
0 = No Fault, 1 = Fault

## 4.11 Brake Info

Message ID: 0x074  
Transmit Rate: 20ms

Table 18: BrakeInfo CAN Message Description.

Byte	Bits	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0	7:0	BRKTRQR<7:0>							
1	15:8	STATNRY	HSASTAT			BRKTRQR<11:8>			
2	23:16	BRKTRQA<7:0>							
3	31:24	PBRAKE		HSAMODE		BRKTRQA<11:8>			
4	39:32	WHLTRQ<7:0>							
5	47:40	—	—	WHLTRQ<13:8>					
6	55:48	AOG<7:0>							
7	63:56	TRACE	TRACA	STABE	STABA	ABSE	ABSA	AOG<9:8>	

bit 0-11	<b>BRKTRQR:</b> Braking Torque Request 0x000 = 0 Nm 0x001 = 4 Nm 0xFFF = 16380 Nm
bit 12-13	<b>HSASTAT:</b> Hill Start Assist Status (See Table 19)
bit 14	<b>STATNRY:</b> Vehicle Stationary 0 = Moving, 1 = Stationary
bit 16-27	<b>BRKTRQA:</b> Braking Torque Actual 0x000 = 0 Nm 0x001 = 4 Nm 0xFFF = 16380 Nm
bit 28-29	<b>HSAMODE:</b> Hill Start Assist Mode (See Table 20)
bit 30-31	<b>PBRAKE:</b> Parking Brake Status (See Table 21)
bit 32-45	<b>WHLTRQ:</b> Wheel Torque Actual 0x1FFF = 32764 Nm 0x0001 = 4 Nm 0x0000 = 0 Nm 0x3FFF = -4 Nm 0x2000 = -32768 Nm
bit 46-47	<b>Unimplemented:</b> Set to '0'
bit 48-57	<b>AOG:</b> Vehicle Acceleration Over Ground Estimate 0x1FF = 17.885 m/s <sup>2</sup> 0x001 = 0.035 m/s <sup>2</sup> 0x000 = 0 m/s <sup>2</sup> 0x3FF = -0.035 m/s <sup>2</sup> 0x200 = -17.92 m/s <sup>2</sup>
bit 58	<b>ABSA:</b> ABS Active, 0 = Inactive, 1 = Active
bit 59	<b>ABSE:</b> ABS Enabled, 0 = Disabled, 1 = Enabled
bit 60	<b>STABA:</b> Stability Control Active, 0 = Inactive, 1 = Active
bit 61	<b>STABE:</b> Stability Control Enabled, 0 = Disabled, 1 = Enabled
bit 62	<b>TRACA:</b> Traction Control Active, 0 = Inactive, 1 = Active
bit 63	<b>TRACE:</b> Traction Control Enabled, 0 = Disabled, 1 = Enabled

Table 19: Enumeration values of the **HSASTAT** signal

Value	Enum
0	INACTIVE
1	FINDING_GRADIENT
2	ACTIVE_PRESSED
3	ACTIVE_RELEASED
4	FAST_RELEASE
5	SLOW_RELEASE
6	FAILED
7	UNDEFINED

Table 20: Enumeration values of the **HSAMODE** signal

Value	Enum
0	OFF
1	AUTO
2	MANUAL
3	UNDEFINED

Table 21: Enumeration values of the **PBRAKE** signal

Value	Enum
0	OFF
1	TRANSITION
2	ON
3	FAULT

## 4.12 Throttle Info

Message ID: 0x075  
Transmit Rate: 10ms

Table 22: ThrottleInfo CAN Message Description.

Byte	Bits	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0	7:0	RPM<7:0>							
1	15:8	RPM<15:8>							
2	23:16	APEDPC<7:0>							
3	31:24	—	—	—	—	—	—	APEDPC<9:8>	
4	39:32	APEDRATE							
5	47:40	—	—	—	—	—	—	—	—
6	55:48	—	—	—	—	—	—	—	—
7	63:56	—	—	—	—	—	—	—	—

bit 0-15      **RPM:** Engine RPM  
0x0000 = 0.00 RPM  
0x0001 = 0.25 RPM  
0xFFFF = 16383.75 RPM

bit 16-25    **APEDPC:** Accelerator Pedal Percent  
0x000 = 0.0 %  
0x001 = 0.1 %  
0x3E7 = 99.9 %

bit 26-31    **Unimplemented:** Set to '0'

bit 32-39    **APEDRATE:** Accelerator Pedal Rate  
0x80 = -5.12 %/ms  
0xFF = -0.04 %/ms  
0x00 = 0 %/ms  
0x01 = 0.04 %/ms  
0x3F = 5.08 %/ms

bit 40-63    **Unimplemented:** Set to '0'

## 4.13 Driver Assist

Message ID: 0x079  
Transmit Rate: 200ms or On Event

Table 23: Wheel Position CAN Message Description.

Byte	Bits	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0	7:0	DECEL							
1	15:8	AEBA	AEBP	AEBE	FCWA	FCWE	—	DECEL_SRC	
2	23:16	—	—	—	—	—	ACCB	ACCE	—

bit 0-7      **DECEL:** Driver Assist Deceleration (AEB/ACC)  
                  0x00 = 0 m/s<sup>2</sup>  
                  0x01 = 0.0625 m/s<sup>2</sup>  
                  0xFF = 15.9375 m/s<sup>2</sup>

bit 8-9      **DECEL\_SRC:** Driver Assist Deceleration Source (AEB/ACC)  
                  0 = None  
                  1 = AEB (Automatic Emergency Braking)  
                  2 = ACC (Adaptive Cruise Control)

bit 10      **Unimplemented:** Set to '0'

bit 11      **FCWE:** FCW Enabled, 0 = Disabled, 1 = Enabled

bit 12      **FCWA:** FCW Active, 0 = Inactive, 1 = Active

bit 13      **AEBE:** AEB Enabled, 0 = Disabled, 1 = Enabled

bit 14      **AEBP:** AEB Precharge, 0 = Inactive, 1 = Active

bit 15      **AEBA:** AEB Active, 0 = Inactive, 1 = Active

bit 16      **Unimplemented:** Set to '0'

bit 17      **ACCE:** ACC Enabled, 0 = Disabled, 1 = Enabled

bit 18      **ACCP:** ACC Braking, 0 = Inactive, 1 = Active

bit 19-23   **Unimplemented:** Set to '0'

## 4.14 License

See the Dataspeed License Manager (DataspeedLM) for more information.  
The bits 16-63 in the License CAN message are multiplexed with the MUX field.

MUX	Description
0x00	Feature 'Base' (base functionality)
0x80	MAC Address
0x81	Build Date string (characters 0-5)
0x82	Build Date string (characters 6-9)
0x83	VIN string (characters 0-5)
0x84	VIN string (characters 6-11)
0x85	VIN string (characters 12-16)

### 4.14.1 Feature: Base

Message ID: 0x07E  
Transmit Rate: 250ms

Table 24: License CAN Message Description.

Byte	Bits	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0	7:0	MUX							
1	15:8	—	—	—	—	—	EXPIRED	TRIAL	READY
2	23:16	—	—	—	—	—	—	TRIAL	ENABLED
3	31:24	—	—	—	—	—	—	—	—
4	39:32	TRIALS USED<7:0>							
5	47:40	TRIALS USED<15:8>							
6	55:48	TRIALS REMAINING<7:0>							
7	63:56	TRIALS REMAINING<15:8>							

bit 0-7	<b>MUX:</b> Multiplexer field, determines representation bits 16-63 0x00 = Feature: Base
bit 8	<b>READY:</b> License Manager ready 0 = Waiting to resolve VIN 1 = Ready
bit 9	<b>TRIAL:</b> Trial license 0 = No features licensed as a trial 1 = One or more features licensed as a trial
bit 9	<b>EXPIRED:</b> Expired license 0 = No feature licenses expired (past firmware build date) 1 = One or more feature licenses expired (past firmware build date)
bit 10-15	<b>Unimplemented:</b> Set to '0'
bit 16	<b>ENABLED:</b> Feature enabled 0 = This feature not licensed 1 = This feature successfully licensed
bit 17	<b>TRIAL:</b> Feature trial 0 = This feature not licensed as a trial 1 = This feature licensed as a trial (regardless of remaining trial counts)
bit 18-31	<b>Unimplemented:</b> Set to '0'
bit 32-47	<b>TRIALS USED:</b> Number of trial counts used for this feature
bit 48-63	<b>TRIALS REMAINING:</b> Number of trial counts remaining for this feature

## 4.14.2 MAC Address

Message ID: 0x07E  
Transmit Rate: 250ms

Table 25: License CAN Message Description.

Byte	Bits	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0	7:0	MUX							
1	15:8	—	—	—	—	—	EXPIRED	TRIAL	READY
2	23:16	MAC0							
3	31:24	MAC1							
4	39:32	MAC2							
5	47:40	MAC3							
6	55:48	MAC4							
7	63:56	MAC5							

bit 0-7      **MUX:** Multiplexer field, determines representation bits 16-63  
0x80 = MAC Address

bit 8      **READY:** License Manager ready  
0 = Waiting to resolve VIN  
1 = Ready

bit 9      **TRIAL:** Trial license  
0 = No features licensed as a trial  
1 = One or more features licensed as a trial

bit 9      **EXPIRED:** Expired license  
0 = No feature licenses expired (past firmware build date)  
1 = One or more feature licenses expired (past firmware build date)

bit 10-15      **Unimplemented:** Set to '0'

bit 16-23      **MAC0:** MAC Address byte 0

bit 24-31      **MAC1:** MAC Address byte 1

bit 32-39      **MAC2:** MAC Address byte 2

bit 40-47      **MAC3:** MAC Address byte 3

bit 48-55      **MAC4:** MAC Address byte 4

bit 56-63      **MAC5:** MAC Address byte 5



## 4.14.3 Build Date (part 0)

Message ID: 0x07E  
Transmit Rate: 250ms

Table 26: License CAN Message Description.

Byte	Bits	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0	7:0	MUX							
1	15:8	—	—	—	—	—	EXPIRED	TRIAL	READY
2	23:16	DATE0							
3	31:24	DATE1							
4	39:32	DATE2							
5	47:40	DATE3							
6	55:48	DATE4							
7	63:56	DATE5							

bit 0-7      **MUX:** Multiplexer field, determines representation bits 16-63  
0x81 = Date part 0

bit 8      **READY:** License Manager ready  
0 = Waiting to resolve VIN  
1 = Ready

bit 9      **TRIAL:** Trial license  
0 = No features licensed as a trial  
1 = One or more features licensed as a trial

bit 9      **EXPIRED:** Expired license  
0 = No feature licenses expired (past firmware build date)  
1 = One or more feature licenses expired (past firmware build date)

bit 10-15      **Unimplemented:** Set to '0'

bit 16-23      **DATE0:** Date string (character 0)

bit 24-31      **DATE1:** Date string (character 1)

bit 32-39      **DATE2:** Date string (character 2)

bit 40-47      **DATE3:** Date string (character 3)

bit 48-55      **DATE4:** Date string (character 4)

bit 56-63      **DATE5:** Date string (character 5)

## 4.14.4 Build Date (part 1)

Message ID: 0x07E  
Transmit Rate: 250ms

Table 27: License CAN Message Description.

Byte	Bits	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0	7:0	MUX							
1	15:8	—	—	—	—	—	EXPIRED	TRIAL	READY
2	23:16	DATE6							
3	31:24	DATE7							
4	39:32	DATE8							
5	47:40	DATE9							
6	55:48	—	—	—	—	—	—	—	—
7	63:56	—	—	—	—	—	—	—	—

bit 0-7      **MUX:** Multiplexer field, determines representation bits 16-63  
0x82 = Date part 1

bit 8      **READY:** License Manager ready  
0 = Waiting to resolve VIN  
1 = Ready

bit 9      **TRIAL:** Trial license  
0 = No features licensed as a trial  
1 = One or more features licensed as a trial

bit 9      **EXPIRED:** Expired license  
0 = No feature licenses expired (past firmware build date)  
1 = One or more feature licenses expired (past firmware build date)

bit 10-15      **Unimplemented:** Set to '0'

bit 16-23      **DATE6:** Date string (character 6)

bit 24-31      **DATE7:** Date string (character 7)

bit 32-39      **DATE8:** Date string (character 8)

bit 40-47      **DATE9:** Date string (character 9)

bit 48-63      **Unimplemented:** Set to '0'

## 4.14.5 VIN (part 0)

Message ID: 0x07E  
Transmit Rate: 250ms

Table 28: License CAN Message Description.

Byte	Bits	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0	7:0	MUX							
1	15:8	—	—	—	—	—	EXPIRED	TRIAL	READY
2	23:16	VIN00							
3	31:24	VIN01							
4	39:32	VIN02							
5	47:40	VIN03							
6	55:48	VIN04							
7	63:56	VIN05							

bit 0-7      **MUX:** Multiplexer field, determines representation bits 16-63  
0x83 = VIN part 0

bit 8      **READY:** License Manager ready  
0 = Waiting to resolve VIN  
1 = Ready

bit 9      **TRIAL:** Trial license  
0 = No features licensed as a trial  
1 = One or more features licensed as a trial

bit 9      **EXPIRED:** Expired license  
0 = No feature licenses expired (past firmware build date)  
1 = One or more feature licenses expired (past firmware build date)

bit 10-15      **Unimplemented:** Set to '0'

bit 16-23      **VIN00:** VIN string (character 0)

bit 24-31      **VIN01:** VIN string (character 1)

bit 32-39      **VIN02:** VIN string (character 2)

bit 40-47      **VIN03:** VIN string (character 3)

bit 48-55      **VIN04:** VIN string (character 4)

bit 56-63      **VIN05:** VIN string (character 5)

## 4.14.6 VIN (part 1)

Message ID: 0x07E  
Transmit Rate: 250ms

Table 29: License CAN Message Description.

Byte	Bits	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0	7:0	MUX							
1	15:8	—	—	—	—	—	EXPIRED	TRIAL	READY
2	23:16	VIN06							
3	31:24	VIN07							
4	39:32	VIN08							
5	47:40	VIN09							
6	55:48	VIN10							
7	63:56	VIN11							

bit 0-7      **MUX:** Multiplexer field, determines representation bits 16-63  
0x84 = VIN part 1

bit 8      **READY:** License Manager ready  
0 = Waiting to resolve VIN  
1 = Ready

bit 9      **TRIAL:** Trial license  
0 = No features licensed as a trial  
1 = One or more features licensed as a trial

bit 9      **EXPIRED:** Expired license  
0 = No feature licenses expired (past firmware build date)  
1 = One or more feature licenses expired (past firmware build date)

bit 10-15      **Unimplemented:** Set to '0'

bit 16-23      **VIN06:** VIN string (character 6)

bit 24-31      **VIN07:** VIN string (character 7)

bit 32-39      **VIN08:** VIN string (character 8)

bit 40-47      **VIN09:** VIN string (character 9)

bit 48-55      **VIN10:** VIN string (character 10)

bit 56-63      **VIN11:** VIN string (character 11)

## 4.14.7 VIN (part 2)

Message ID: 0x07E  
Transmit Rate: 250ms

Table 30: License CAN Message Description.

Byte	Bits	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0	7:0	MUX							
1	15:8	—	—	—	—	—	EXPIRED	TRIAL	READY
2	23:16	VIN12							
3	31:24	VIN13							
4	39:32	VIN14							
5	47:40	VIN15							
6	55:48	VIN16							
7	63:56	—	—	—	—	—	—	—	—

bit 0-7      **MUX:** Multiplexer field, determines representation bits 16-63  
0x85 = VIN part 2

bit 8      **READY:** License Manager ready  
0 = Waiting to resolve VIN  
1 = Ready

bit 9      **TRIAL:** Trial license  
0 = No features licensed as a trial  
1 = One or more features licensed as a trial

bit 9      **EXPIRED:** Expired license  
0 = No feature licenses expired (past firmware build date)  
1 = One or more feature licenses expired (past firmware build date)

bit 10-15      **Unimplemented:** Set to '0'

bit 16-23      **VIN12:** VIN string (character 12)

bit 24-31      **VIN13:** VIN string (character 13)

bit 32-39      **VIN14:** VIN string (character 14)

bit 40-47      **VIN15:** VIN string (character 15)

bit 48-55      **VIN16:** VIN string (character 16)

bit 56-63      **Unimplemented:** Set to '0'

## 4.15 Version

Message ID: 0x07F  
Transmit Rate: 1000ms

Table 31: Version CAN Message Description.

Byte	Bits	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0	7:0	MODULE							
1	15:8	PLATFORM							
2	23:16	MAJOR<7:0>							
3	31:24	MAJOR<15:8>							
4	39:32	MINOR<7:0>							
5	47:40	MINOR<15:8>							
6	55:48	BUILD<7:0>							
7	63:56	BUILD<15:8>							

bit 0-7      **MODULE:** Module enumeration  
              0x03 = Steering Module  
              Other = Ignore, not this module

bit 8-15     **PLATFORM:** Vehicle platform enumeration  
              0x01 = FORD\_P5  
              Other = Ignore, not this vehicle platform

bit 16-31    **MAJOR:** Firmware version major increment

bit 32-47    **MINOR:** Firmware version minor increment

bit 48-63    **BUILD:** Firmware version build increment

## 5 Function

- **Modifying the Steering Signals:** The by-wire interface modifies the steering signals when power is applied and the required CAN messages are received. The vehicle steering system will function regardless of the CAN messaging and applied power to the by-wire interface.
- **Power-off State:** Without power applied, the hardware passes signals through unaltered.
- **Disabled State:** In the disabled state, steering signals are not modified. This corresponds to  $EN = 0$ . The by-wire interface does not respond to any SCMD until the enable bit (EN) is set to 1.
- **Power-up State:** The by-wire interface powers up in the disabled state.  $EN = 0$ .
- **Watchdog Timer:** If the by-wire interface does not receive a steering command message within 100ms, the by-wire interface enters the disabled state.
- **Driver Override (Steering):** If the system senses torque on the steering wheel from the driver, control is given to the driver by entering the driver override state. This corresponds to  $OVERRIDE = 1$  and  $EN = 0$  in the CAN steering report message. This can be cleared by toggling EN from 0 to 1, or by setting CLEAR to 1 in the CAN steering command message.
- **Audible Warning:** The steering module simultaneously activates the front and rear parking proximity warning chimes for one second to indicate an unintentional transition from computer control back to manual control. This is defined as a transition of the EN bit from 1 to 0 in any of the report messages for brake/throttle/steering/shifting, without a corresponding transition in the command message. An unintentional transition could be caused by an override, timeout, fault, or any other unexpected behavior. The brake and throttle report messages are received on the CAN bus from the external throttle/brake module.

## 6 Supported Vehicles

The Steering By-Wire interface has been tested on the Ford F-150 for model year 2018 and 2019.

## 7 Watchdog Counter

The watchdog counter is an optional feature enabled by incrementing the COUNT bits to assist in compliance with California autonomous vehicle requirements. This is separate from the 100ms watchdog timeout always present for each command message. Each module monitors its own state and the state of all other modules for error conditions. To clear a watchdog counter event, press the OK button on the left side of the steering wheel or cycle power to all modules.

### 7.1 Fault Conditions

- Count is not incremented, or count is incremented more than 3 (this allows up to 2 dropped messages)
- Command timeout after 100ms (catches main computer crash, power loss, or disconnect)
- Report timeout after 100ms (catches failure of embedded firmware)
- Transition from enabled to disabled (catches unexpected transfer of control to the driver)
  - This fault condition can be disabled with the DbwConfig GUI.
- Vehicle must be out of park or moving for any of these conditions to set off an alert

### 7.2 Fault Actions

- Normal driver override audible and visual alert for one second (sets off the front park aid warning)
- Apply small amount of braking until the driver takes control with the brake pedal, throttle pedal, but not the steering wheel. The applied braking value is 1 m/s<sup>2</sup>. The braking value can be changed with the DbwConfig GUI.
- Flash the passenger airbag ON and OFF lights until the alert is cleared to show that the watchdog is faulted
- All commands to all subsystems are ignored until the alert is cleared



## APPENDIX A: REVISION HISTORY

### Revision A-01 (August 2015)

#### Modifications:

1. Initial release of this document.

### Revision A-02 (October 2015)

#### Modifications:

1. Added GPS, suspension height, tire pressure, and fuel level CAN messages.
2. Added product image.

### Revision A-03 (December 2015)

#### Modifications:

1. Added steering velocity.

### Revision A-04 (March 2016)

#### Modifications:

1. Clarified FLTCON bit and CD pins.
2. Added FLTCAL bit for steering calibration fault.
3. Removed suspension message.
4. Added doors and seat belts to Miscellaneous report.
5. Added Surround message (sonars, BLIS, and CTA).
6. Added Brake Info message.

### Revision A-05 (April 2016)

#### Modifications:

1. Added IGNORE bit to optionally ignore driver override and periodically try and regain steering control.
2. Changed DRIVER bit to DRIVER and OVERRIDE bits (activity and enough activity for an override).
3. Added additional steering wheel buttons.
4. Added optional watchdog counter.

### Revision A-06 (August 2016)

#### Modifications:

1. Corrected FLTSNR and ENSNR bits in surround CAN message.
2. Added Throttle Info CAN message.

### Revision A-07 (November 2016)

#### Modifications:

1. Added QUIET bit in steering command CAN message.
2. Added version CAN message.

### Revision A-08 (December 2016)

#### Modifications:

1. Changed wheel speeds to signed values.

## **Revision A-09 (August 2017)**

### Modifications:

1. Added license CAN message (with VIN).
2. Added steering wheel left D-Pad buttons.
3. Added Watchdog Counter applied braking value.
4. Added threshold for driver override bit in steering report.
5. Added rejected enumeration in gear report.
6. Removed driver activity bit in steering report.
7. Replaced FLTCON bit with TMOUT bit (timeout).
8. Replaced Suspension Report with Wheel Position Report.
9. Updated supported vehicle model year range to 2017.

## **Revision A-10 (October 2017)**

### Modifications:

1. Added notes about gear shift and turn-signal command rejection when an override is active.

## **Revision A-11 (October 2017)**

### Modifications:

1. Added note about requirements to engage steering.

## **Revision A-12 (January 2018)**

### Modifications:

1. Added FLTPWR bit to steering report.
2. Added wheel position conversion factor.
3. Updated audible warning to include all unintentional transitions to disabled.
4. Updated supported vehicle model year range to 2018.

## **Revision A-13 (June 2018)**

### Modifications:

1. Added RES+ and RES- cruise control buttons to miscellaneous report (RINC and RDEC).

## **Revision A-14 (August 2018)**

### Modifications:

1. Added PLATFORM field to version message.

## **Revision A-15 (October 2018)**

### Modifications:

1. Added OTEMP to miscellaneous report.
2. Updated supported vehicle model year range to 2019.
3. Removed vehicle requirement of Active Park Assist (APA). Modern firmware automatically enables APA if not already enabled.

## **Revision A-16 (November 2018)**

### Modifications:

1. Added ULC messages.
2. Added notes about parameters (overrides and watchdog counter).
3. Added mechanical drawing.
4. Updated product photo.

**Revision A-17 (March 2019)****Modifications:**

1. Fixed CAN termination resistance that was mistakenly changed to false.
2. Changed steering torque override threshold to 4.5 Nm.
3. Removed GPS messages (not supported on this platform).
4. Updated Watchdog Counter braking value.